

LAWS OF MOTION

(Circular Motion)

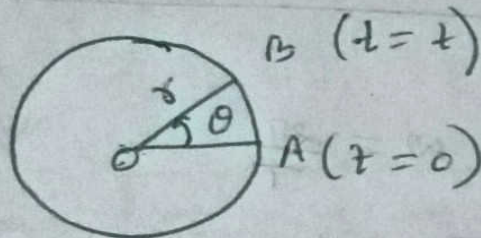
Important terms in circular motion:

1) Angular displacement (θ)

The angle described by the particle about the axis of rotation (or centre O) in a given time is called the angular displacement (θ).

$$\angle AOB = \theta$$

Unit \rightarrow Radian



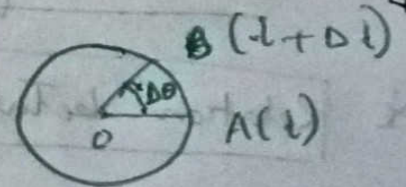
2) Angular speed (ω)

The ratio of angular displacement to the time taken is called angular speed. Denoted by ω (omega)

ω (omega)

Unit \rightarrow radian/sec

$$\omega = \frac{\theta}{t}$$

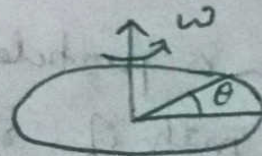


3) Time-period (T)

Time taken by a particle to complete one rotation is called time-period (T)

$$\omega = \frac{2\pi}{T} \text{ rad/s}$$

$$\therefore \theta = 2\pi \text{ when } t = T$$



A) Frequency (ν)

The number of rotations completed by a particle in one sec is called frequency.

$$\boxed{\nu = \frac{1}{T}}$$

Unit is Hertz (Hz) or sec^{-1}

* Relation between ω and ν

We know,

$$\omega = \frac{2\pi}{T}$$

$$\therefore T = \frac{1}{\nu}$$

$$\therefore \boxed{\omega = 2\pi\nu}$$

Direction of ω \rightarrow Along the axis of rotation.

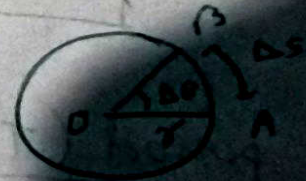
* Relation between linear speed and angular speed

- Let us consider a particle moving in a circular path of radius r .

Let it travel linear distance

' DS ' in time ' Δt ' with

linear speed v and angular speed ω .



Let $\Delta\theta$ be the angular displacement in time Δt .

then

$$\omega = \frac{\Delta\theta}{\Delta t}$$

$$v = \frac{\Delta s}{\Delta t}$$

But from figure.

$$\Delta s = r \Delta\theta$$

$$\therefore v = r \left(\frac{\Delta\theta}{\Delta t} \right)$$

$$v = r\omega$$

In vector form,

$$\vec{v} = \vec{r} \times \vec{\omega}$$

Angular acceleration (α)

Rate of change of angular velocity of a particle.

$$\omega = \frac{d\theta}{dt}$$

$$\alpha = \frac{d\omega}{dt} = \frac{d}{dt} \left(\frac{d\theta}{dt} \right)$$

$$\alpha = \frac{d^2\theta}{dt^2}$$

* Relation between linear acceleration (a) and angular acceleration (α)

We have,

$$\text{linear acceleration, } a = \frac{dv}{dt}$$

$$\text{but } v = r\omega$$

$$\Rightarrow a = \frac{d(r\omega)}{dt}$$

$$\left(\frac{dr}{dt} \omega + r \frac{d\omega}{dt} \right)$$

$$= r\alpha \quad \left[\because \alpha = \frac{d\omega}{dt} \right]$$

In vector form $\boxed{\vec{a} = \vec{r} \times \vec{\alpha}}$

For uniform / constant angular velocity

$$\frac{d\omega}{dt} = 0$$

$$\therefore \boxed{\alpha = 0}$$

i.e. $\omega = \text{constant} \rightarrow \frac{d\omega}{dt} = 0$ or $\alpha = 0$

$$\left(\frac{d\omega}{dt} \right) \frac{b}{+b} = \frac{d\omega}{dt} = 0$$

$$\boxed{\frac{d\omega}{dt} = 0}$$

Direction of $\Delta \vec{v}$ \longrightarrow Towards centre of circle

Average acceleration of the particle is

$$\vec{a}_{av} = \frac{\Delta \vec{v}}{\Delta t} \cdot [\text{towards centre}]$$

From triangles.

$$\longrightarrow \text{①}$$

$\Delta O B$ and $P O B$ which are similar with vertex angle θ , we can write

$$\frac{|\Delta \vec{v}|}{|\Delta \vec{r}|} = \frac{v}{r}$$

$$\Rightarrow \Delta \vec{v} = \frac{v}{r} \Delta \vec{r}$$

\therefore equation ① implies

$$\vec{a}_{av} = \frac{\Delta v}{\Delta t} = \frac{v}{r} \frac{|\Delta \vec{r}|}{\Delta t} \longrightarrow \text{②}$$

When $\Delta t \rightarrow 0$, Arc $AB \approx |\Delta \vec{r}|$

$$\text{i.e. } \left[\lim_{\Delta t \rightarrow 0} \frac{ds}{dt} = v \right] \longrightarrow \text{③}$$

\therefore Instantaneous acceleration

$$a = \lim_{\Delta t \rightarrow 0} |\vec{a}_{av}| = \lim_{\Delta t \rightarrow 0} \frac{v}{r} \frac{|\Delta \vec{r}|}{\Delta t}$$

$$\Rightarrow a = \frac{v}{r} \lim_{\Delta t \rightarrow 0} \left| \frac{\Delta \vec{v}}{\Delta t} \right| = \frac{v}{r} \times v \quad [\text{from eq (3)}]$$

$$\Rightarrow \boxed{a = \frac{v^2}{r}} \quad \text{---} \quad (4)$$

Direction of a is towards the centre, so ~~we~~ it is called as centripetal acceleration.

Again, we know

$$v = r\omega$$

$$\therefore a = \frac{v^2}{r} = \frac{(r\omega)^2}{r}$$

$$= r\omega^2$$

$$= r(2\pi\nu)^2 \quad [\because \omega = 2\pi\nu]$$

$$\boxed{a = r 4\pi^2 \nu^2}$$

Equations of motion in circular/linear motion

Linear

- ① $s = ut$
- ② $s = ut + \frac{1}{2}at^2$
- ③ $v = u + at$
- ④ $v^2 - u^2 = 2as$

Circular

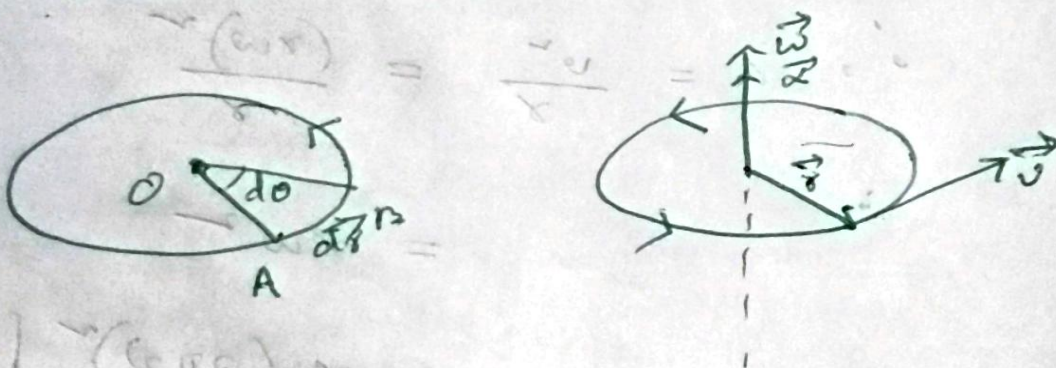
$$\theta = \omega_0 t$$

$$\theta = \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\omega = \omega_0 + \alpha t$$

$$\omega^2 - \omega_0^2 = 2\alpha\theta$$

Non-uniform circular motion



Let us consider a particle moves in a circular path of radius r with angular velocity $\vec{\omega}$ in anticlockwise direction. From A to B, let linear displacement is \vec{ds} and angular displacement is $\vec{d\theta}$

$$d\vec{r} = d\vec{\omega} \times \vec{r}$$

$$\frac{d\vec{r}}{dt} = \frac{d\vec{\omega}}{dt} \times \vec{r}$$

$$\Rightarrow \boxed{\vec{v} = \vec{\omega} \times \vec{r}} \quad \longrightarrow \quad (1)$$

Differentiating with respect to time.

$$\frac{d\vec{v}}{dt} = \frac{d}{dt} (\vec{\omega} \times \vec{r})$$

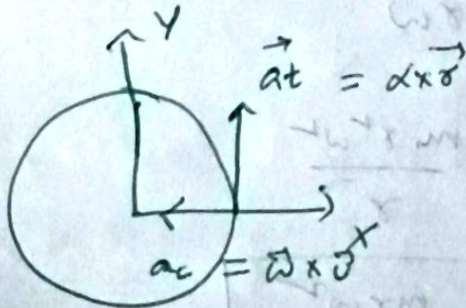
$$= \frac{d\vec{\omega}}{dt} \times \vec{r} + \vec{\omega} \times \frac{d\vec{r}}{dt}$$

$$\Rightarrow \boxed{\vec{a} = \vec{\alpha} \times \vec{r} + \vec{\omega} \times \vec{v}}$$

Here

$$\vec{\alpha} \times \vec{r} = a_t \quad [\text{tangential}]$$

$$\vec{\omega} \times \vec{v} = a_c \quad [\text{centripetal}]$$



$$\boxed{\vec{a} = a_t + a_c}$$

Dynamics of circular motion

Centripetal force:

The force which deviates a body from its linear path to move along a circular path is called centripetal force. It is directed towards the centre of the circular path.

We know,

$$a = \frac{v^2}{r} \quad [\text{in eqn (4)}]$$

Again,

$$F = ma.$$

$$\Rightarrow F = \frac{mv^2}{r}$$

$$\text{If } v = r\omega.$$

$$F = \frac{m r^2 \omega^2}{r}$$

$$F = m r \omega^2$$

Again $\omega = \frac{2\pi}{T}$

$$F = m r \left(\frac{2\pi}{T} \right)^2$$

$$F = \frac{4\pi^2 m r}{T^2}$$

Again, $\frac{v}{r} = \omega$

$$F = 4\pi^2 m r \omega^2$$

Example:

① Gravitational force of attraction between Sun and earth

② Electrostatic force of attraction between electron and nucleus

* Centrifugal force

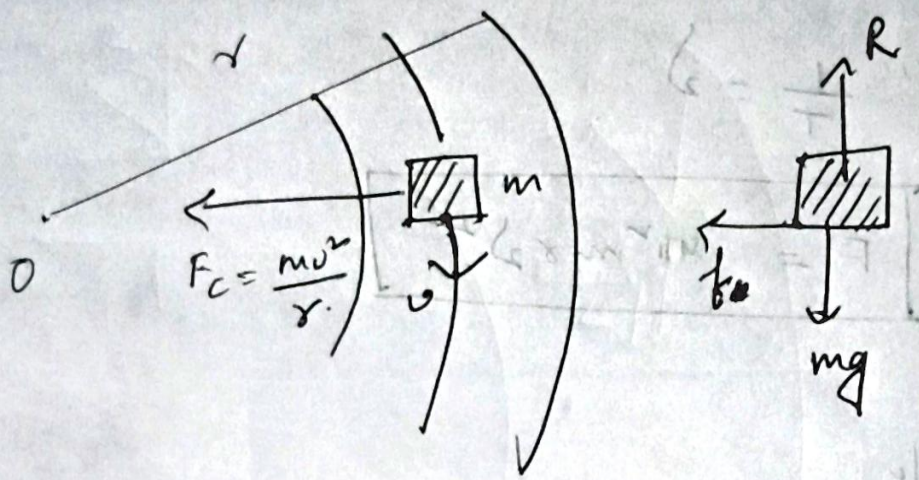
The force that tends to move the bodies / particles of a rotating frame away from the axis of rotation is called centrifugal force.

$$F_{\text{centrifugal}} = m v^2 / r$$

* Centrifugal force is a fictitious/pseudo force that comes into play in an accelerated frame of reference.

Examples of Circular motion

(1) Car on a level circular road.



Let a car moves in a flat horizontal circular road of radius r .

Forces acting on the car are:

(1) $W = mg \downarrow$

(2) R (normal reaction) \uparrow

(3) Friction force f between tyres of car and road.

Here $R = mg$ \because car is not moving in vertical direction.

In a circular path

$$F_c = \frac{mv^2}{r}$$

Here, $f = \mu R = \mu mg$

$$\mu f = F_c$$

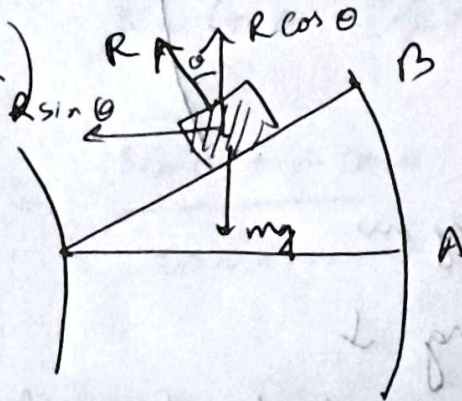
$$\Rightarrow \frac{mv^2}{r} = \mu mg$$

$$\Rightarrow v = \sqrt{\mu rg}$$

Important

② Banked circular road.

(neglecting friction)



Here forces acting are -

① $w = mg \downarrow$

② R perpendicular to the surface of road \uparrow

Resolving into $R \sin \theta$ & $R \cos \theta$

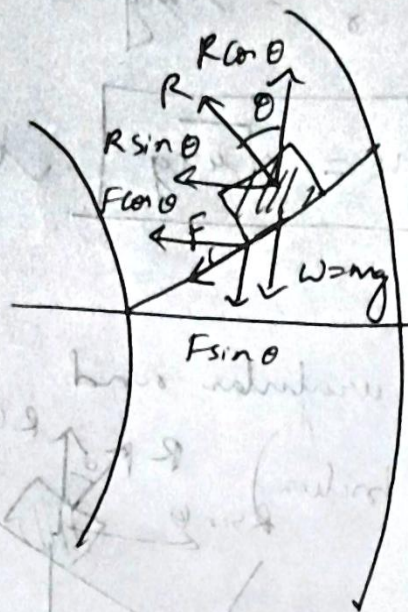
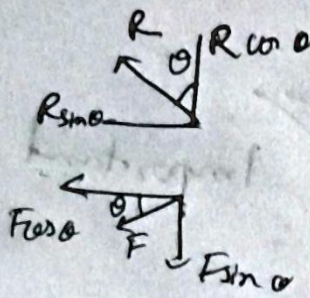
We have $R \sin \theta = \frac{mv^2}{r}$, $R \cos \theta = mg$

$$\tan \theta = \frac{v^2}{rg}$$

$$\Rightarrow v^2 = \tan \theta rg$$

$$\Rightarrow v = \sqrt{rg \tan \theta}$$

(3) Banked circular road (considering friction)



Forces acting on

① $W = mg \downarrow$

② R perpendicular to surface

③ force of friction F betⁿ tyre & road.

For equilibrium.

$$mg + F \sin \theta = R \cos \theta$$

$$mg = R \cos \theta - F \sin \theta \quad \text{--- ①}$$

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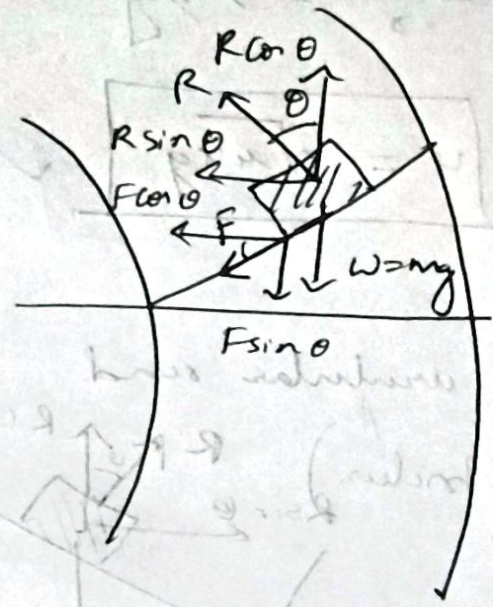
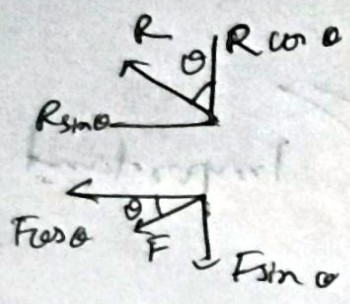
$$\tan \theta = \frac{v^2}{rg}$$

$$v^2 = rg \tan \theta$$

$$v = \sqrt{rg \tan \theta}$$

(1)

(3) Banked circular road (considering friction)



Forces acting on

- ① $W = mg \downarrow$
- ② R perpendicular to surface
- ③ force of friction F acts \sim tyres & road.

For equilibrium.

$$mg + F \sin \theta = R \cos \theta$$

$$mg = R \cos \theta - F \sin \theta$$

$(R \sin \theta + F \cos \theta)$ towards centre of the road
 which provides centripetal force $\frac{mv^2}{r}$

$$\frac{mv^2}{r} = F \cos \theta + R \sin \theta \quad \text{--- (2)}$$

$$\text{(2)} \div \text{(1)}$$

$$\Rightarrow \frac{\frac{mv^2}{r}}{mg} = \frac{R \sin \theta + F \cos \theta}{R \cos \theta - F \sin \theta}$$

$$\Rightarrow \frac{v^2}{rg} = \frac{R [\sin \theta + \frac{F}{R} \cos \theta]}{R [\cos \theta - \frac{F}{R} \sin \theta]}$$

$$\Rightarrow \frac{v^2}{rg} = \frac{\sin \theta + \mu \cos \theta}{\cos \theta - \mu \sin \theta} \quad \left[\begin{array}{l} \because \mu R = F \\ \text{or } \mu = F/R \end{array} \right]$$

$$\Rightarrow \frac{v^2}{rg} = \frac{\tan \theta + \mu}{1 - \mu \tan \theta} \quad \left[\begin{array}{l} \text{dividing by } \cos \theta \\ \text{on numerator \& } \\ \text{denominator} \end{array} \right]$$

$$v = \left[\frac{rg(\tan \theta + \mu)}{1 - \mu \tan \theta} \right]^{\frac{1}{2}}$$